

Final Year Project

Communication between Robots and a Computer via the Internet

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Aim:

Develop a software platform (Network Library) on Linux for remote control of robots via the Internet.

=> Demonstration on a real robot

=> Explore the feasibility of using the Internet to control robots

Why this Project?

Organisation of the Internet

Packets (postal service)

=> Random Time Delay

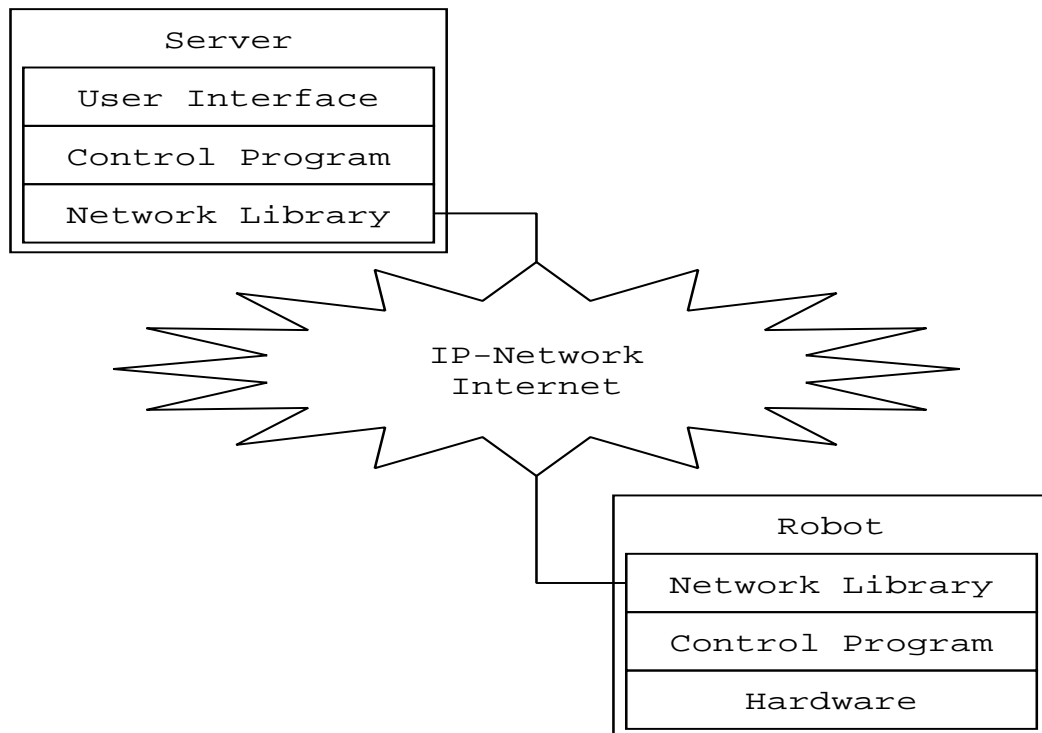
Analysis/Measurement:

- basic time delay depends on distance
- increasing depends on the daytime and period (school-hours, holiday)
- local school network caused main time delay

Modes to control a robot:

- Direct Control
- Supervisory Control:
give target

Basic Structure:



Project Status

- The library is implemented
- An example robot can be controlled
- Completing documentation and report remains

Conclusions

- Challenges
- „Have a plan“